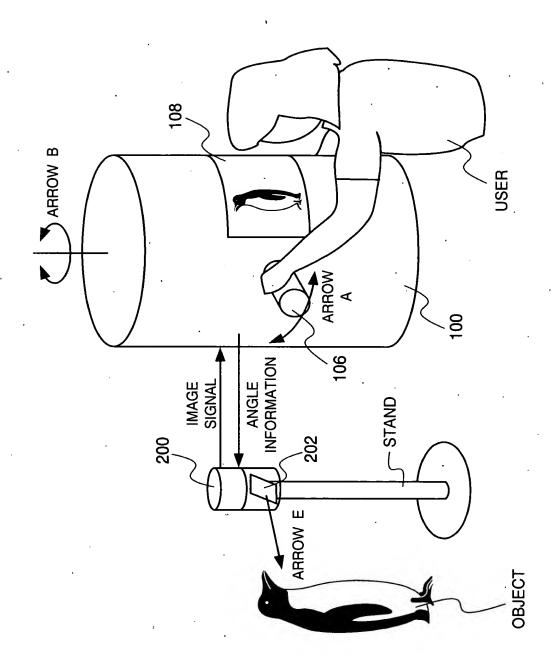
FIG. 1



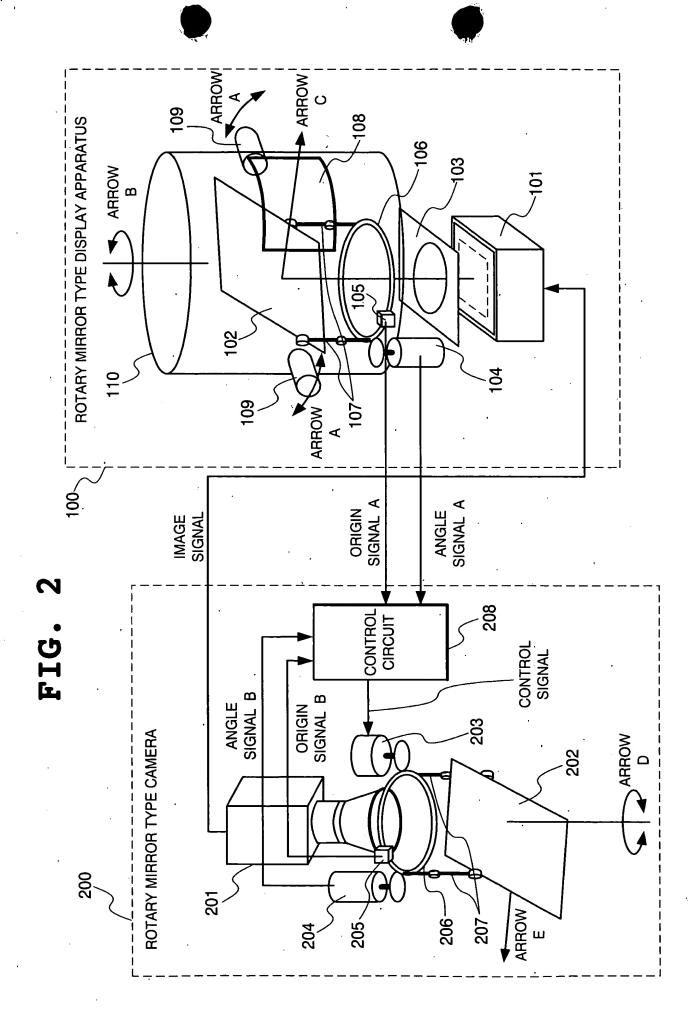


FIG. 3

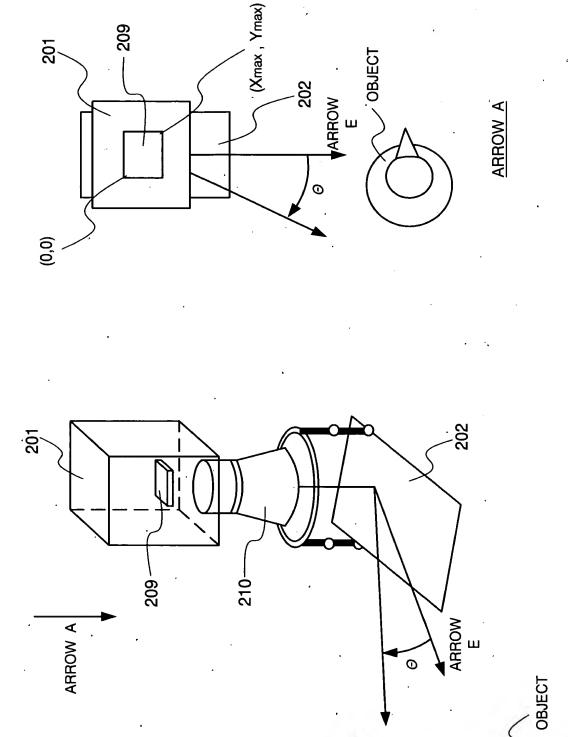
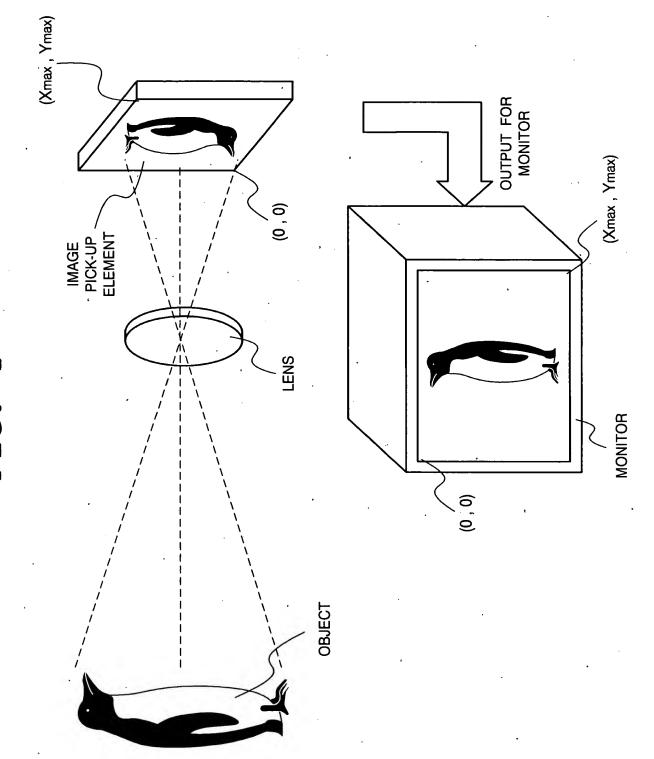


FIG. 4



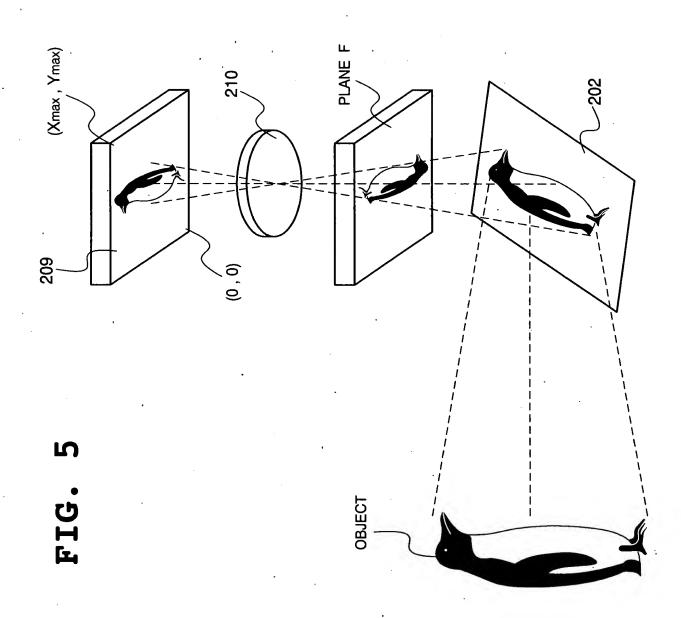
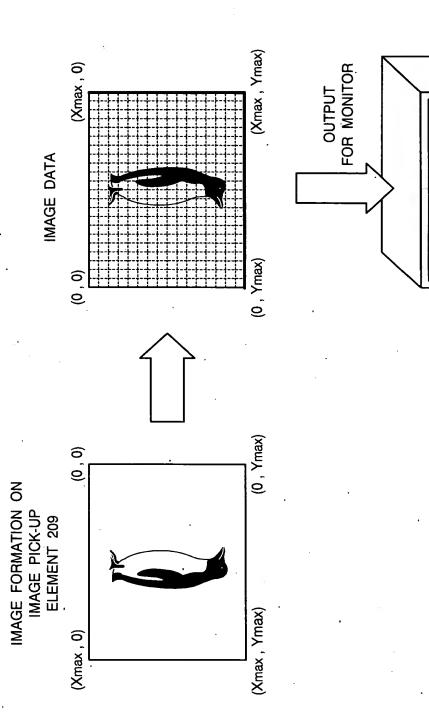


FIG. 6



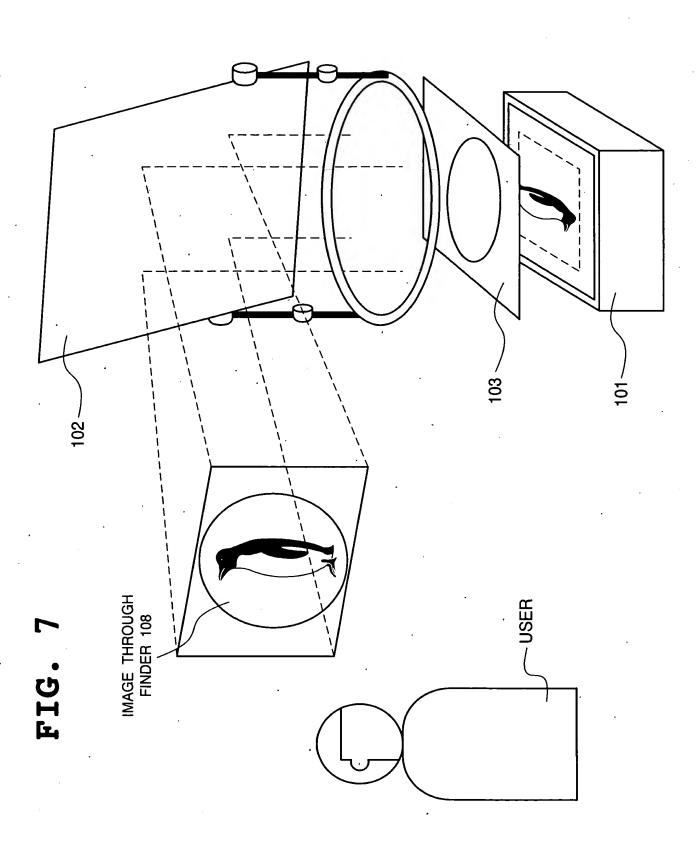


FIG. 8

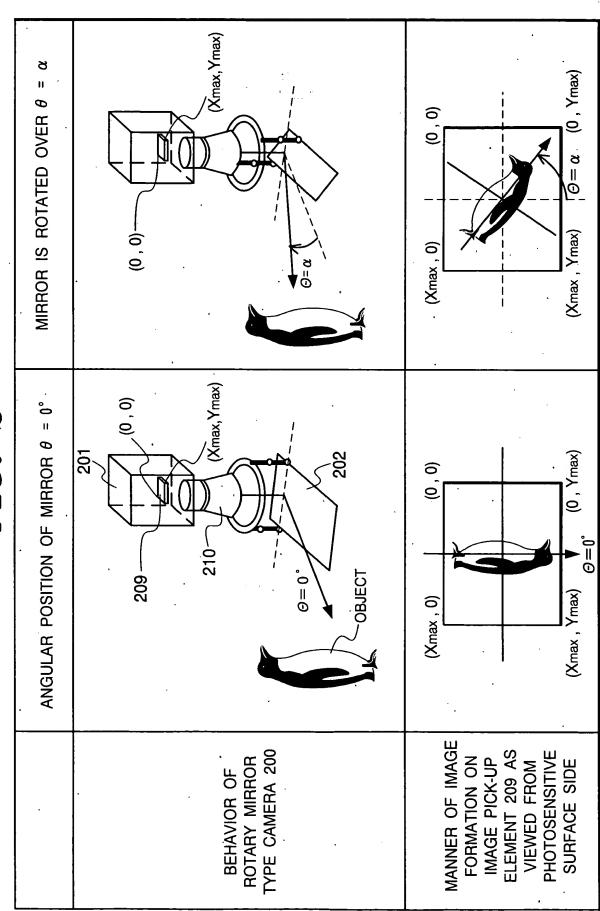
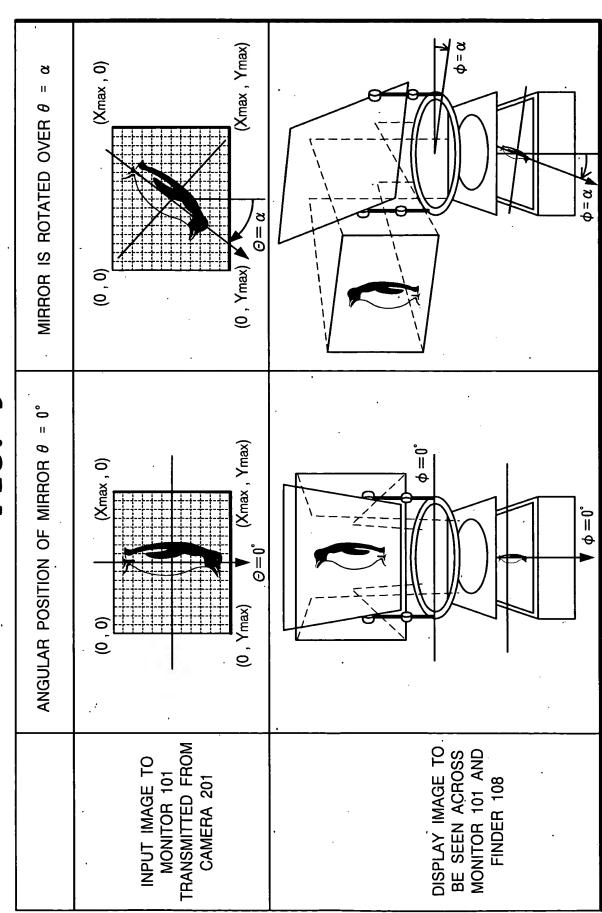


FIG. 9



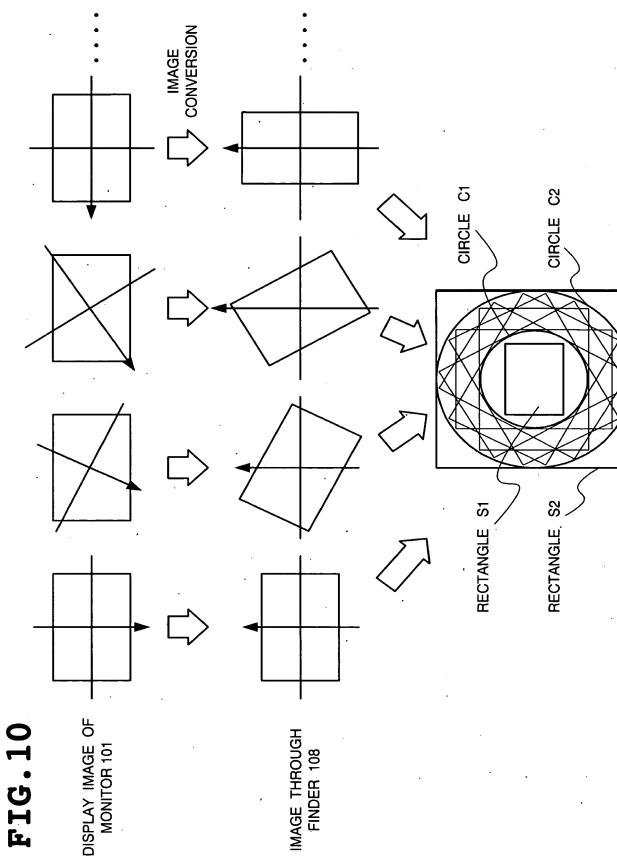
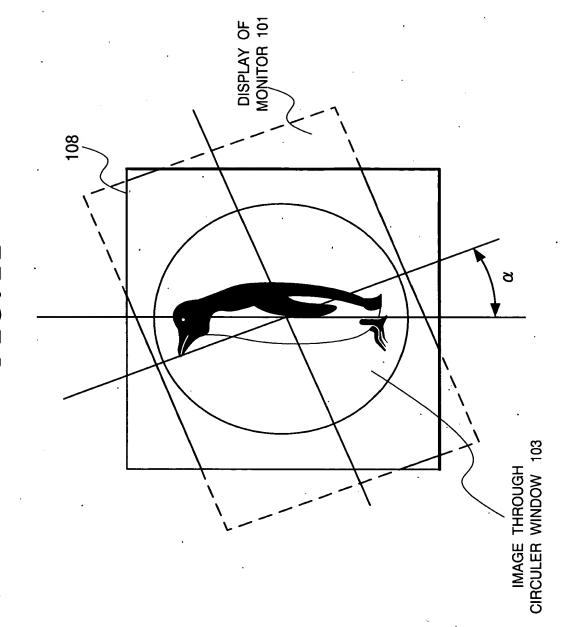
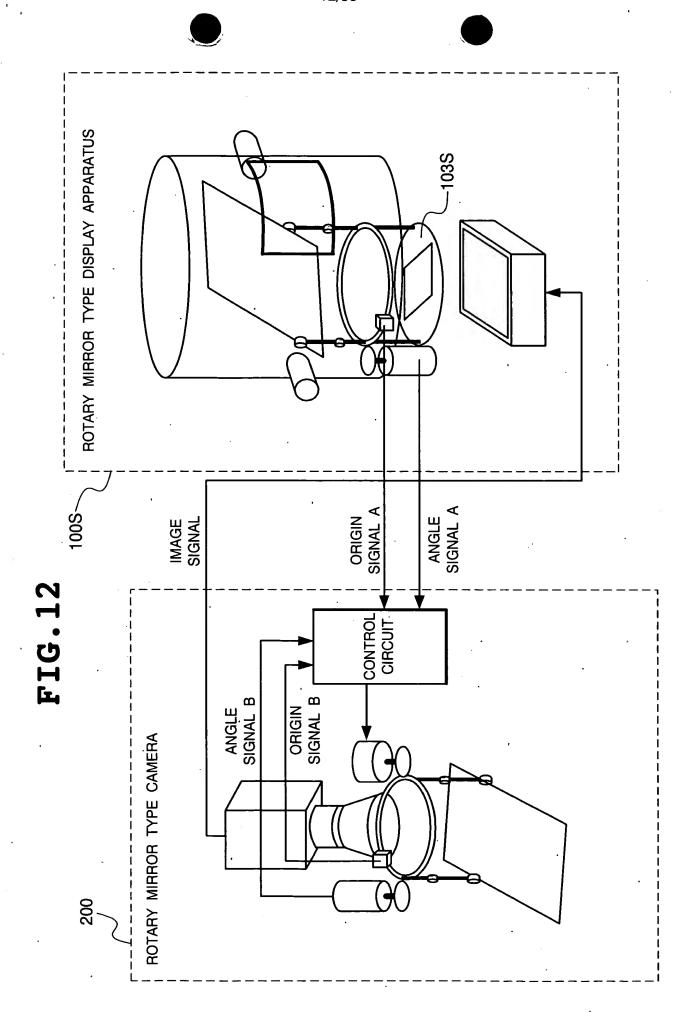


FIG. 11





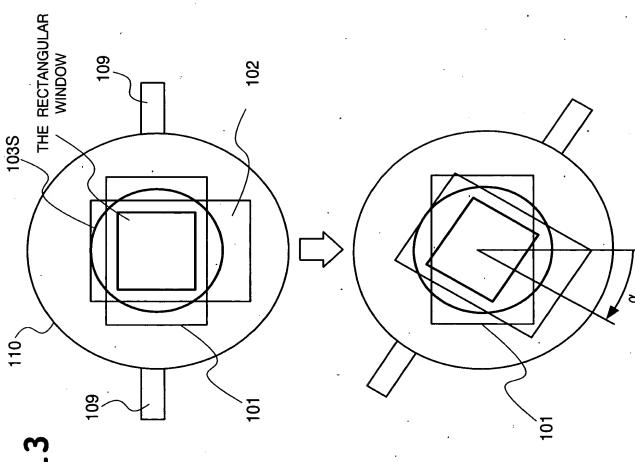


FIG. 13

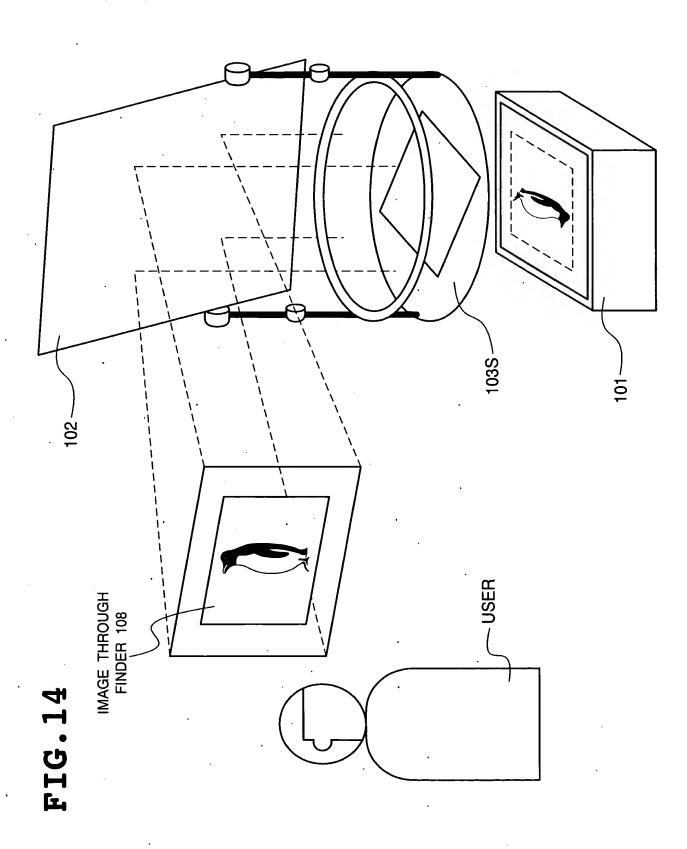
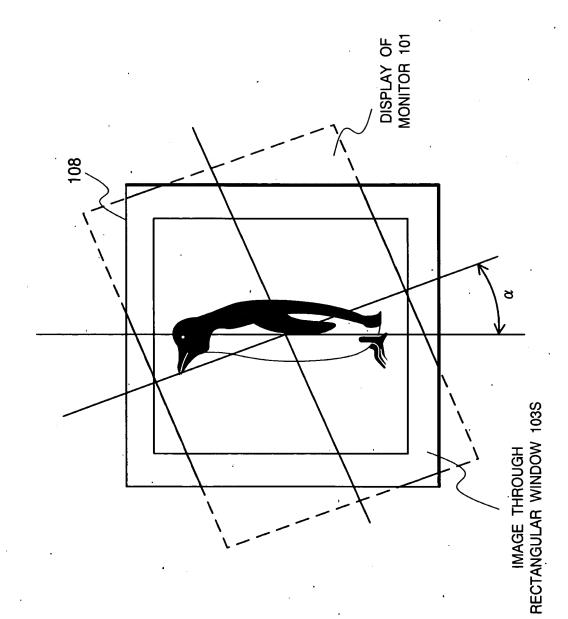
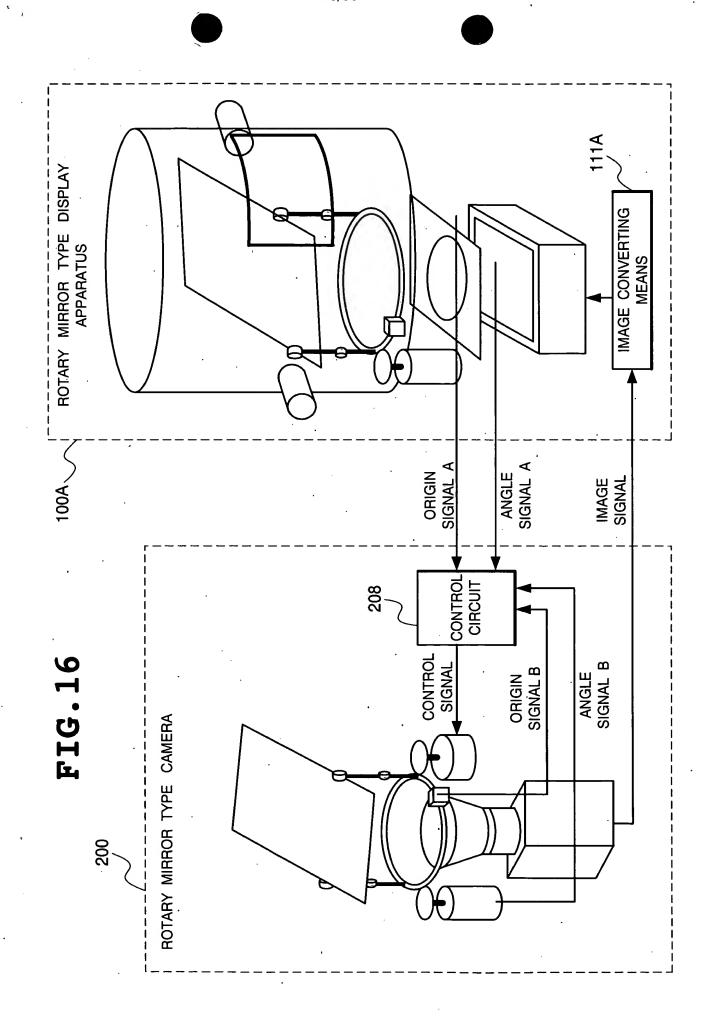
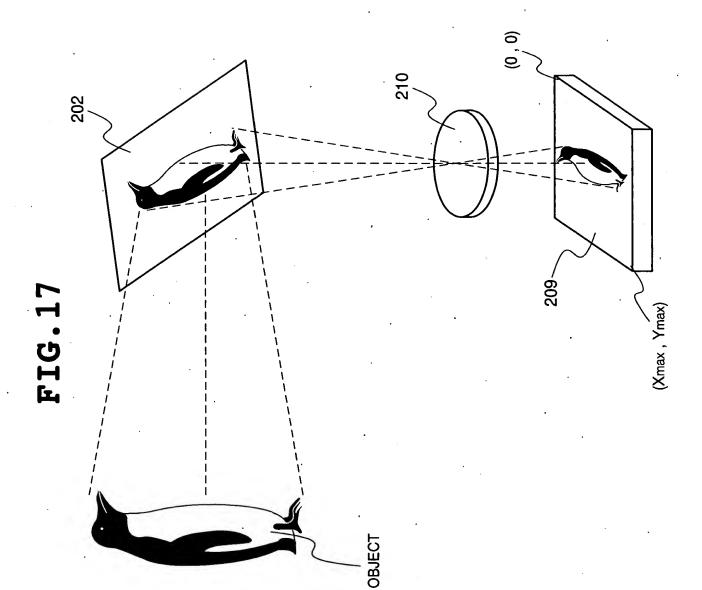
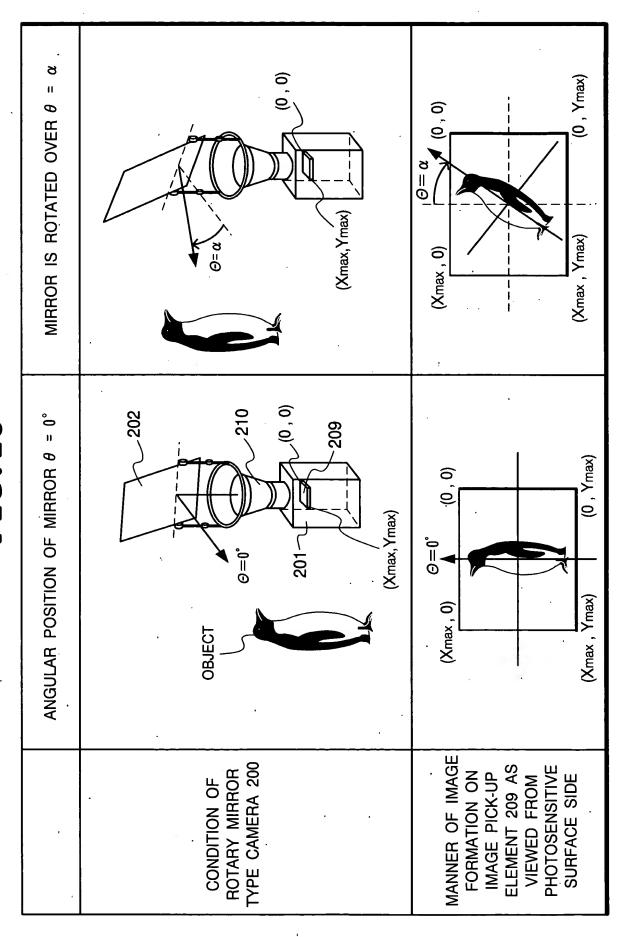


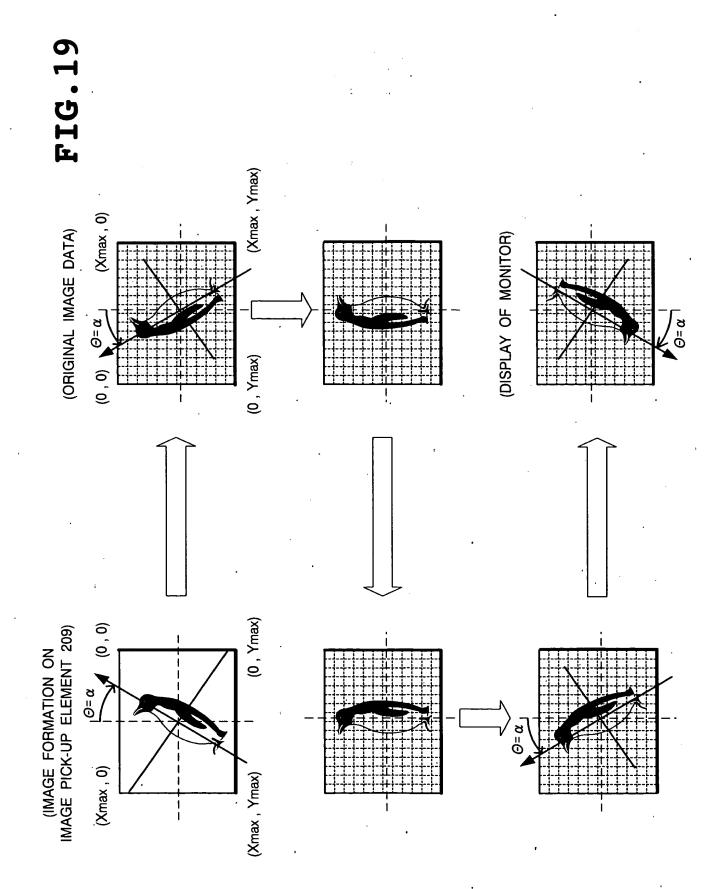
FIG. 15

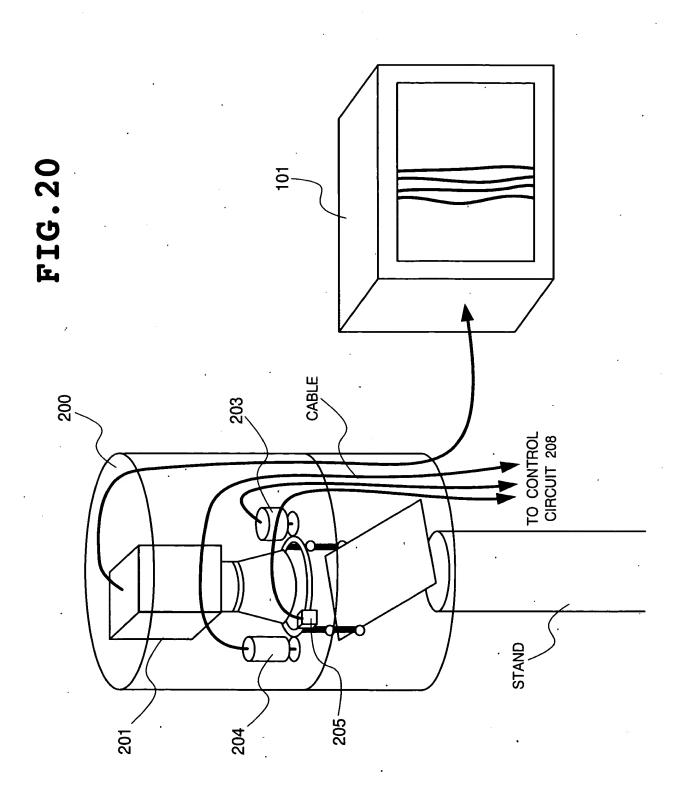


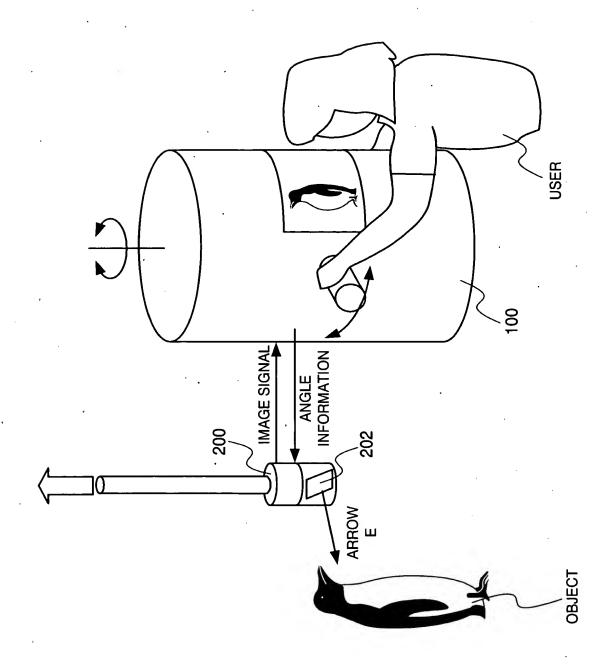


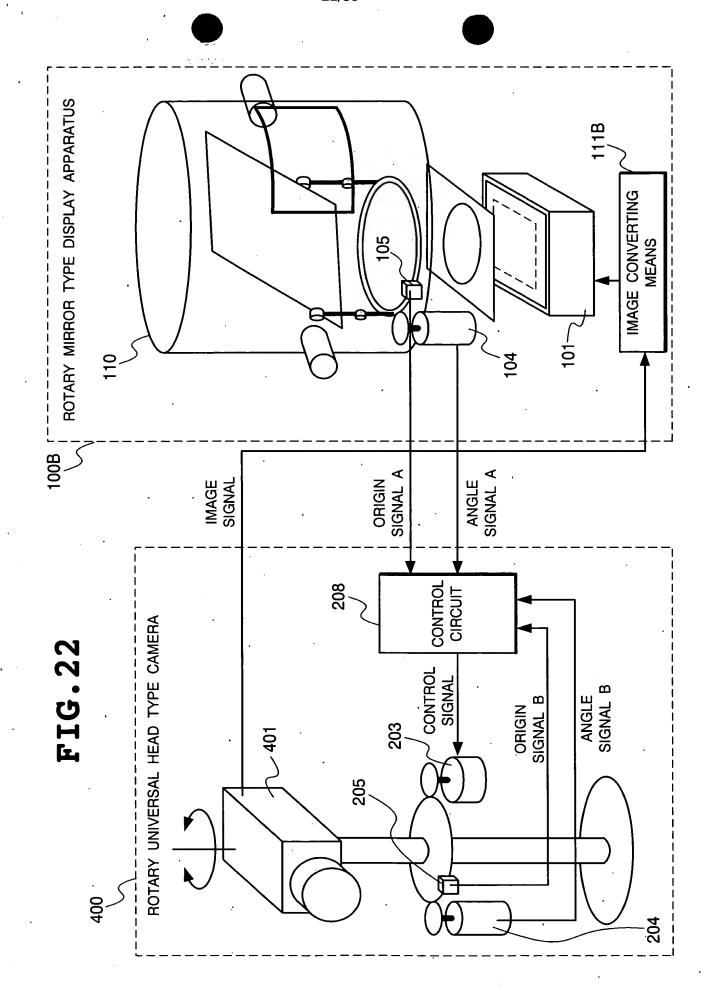






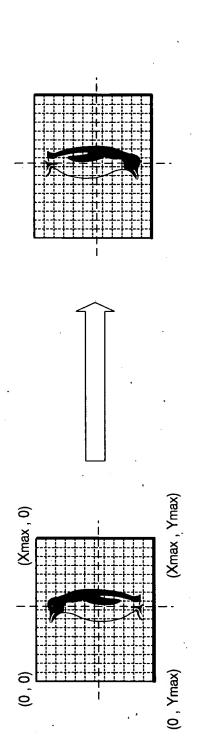


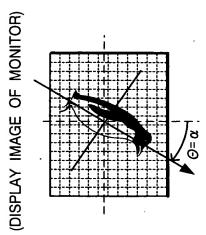


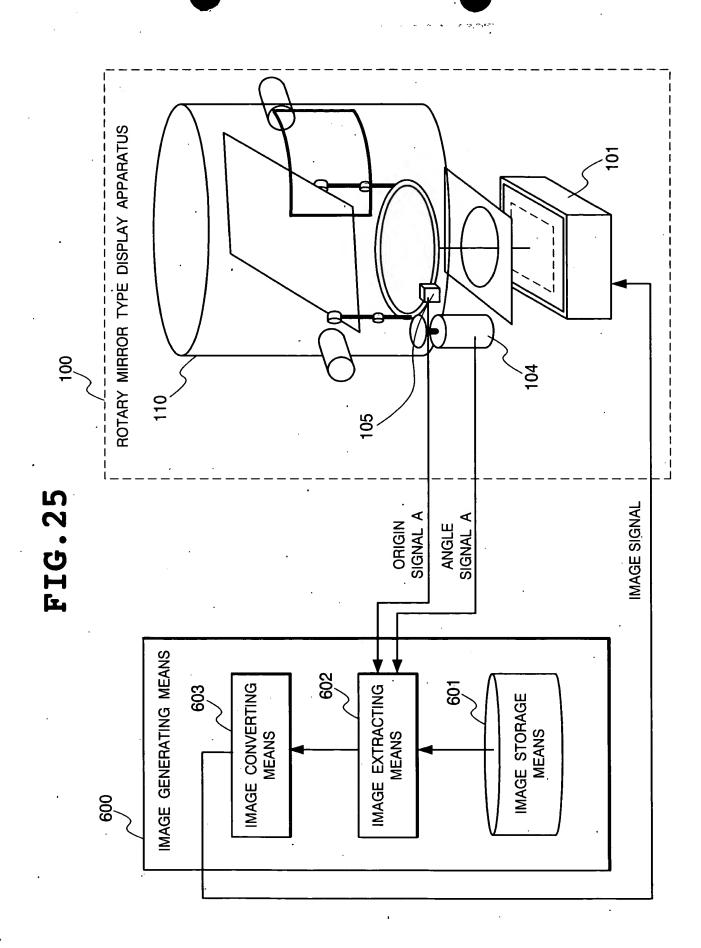


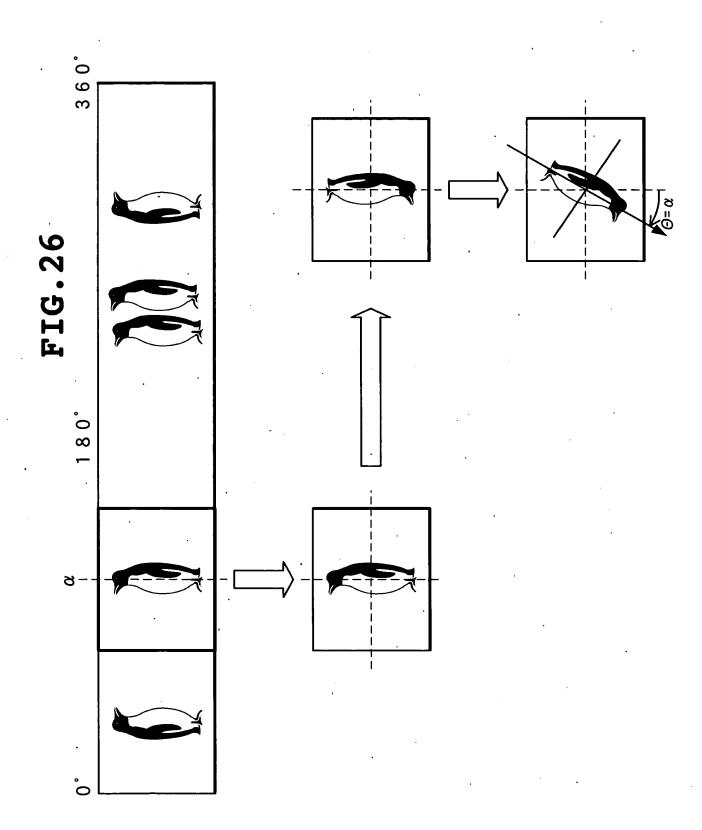
CAMERA 401 IS ROTATED OVER $\theta = \alpha$		(0, 0) (Xmax, 0) (O, Vmax) (Xmax, Ymax)
ANGULAR POSITION OF CAMERA 401 θ = 0°	OBJECT 401	(0, 0) (Xmax, 0)
	CONDITION OF ROTARY UNIVERSAL HEAD TYPE CAMERA 400	ORIGINAL IMAGE OUTPUT FROM CAMERA 401

(ORIGINAL IMAGE DATA)

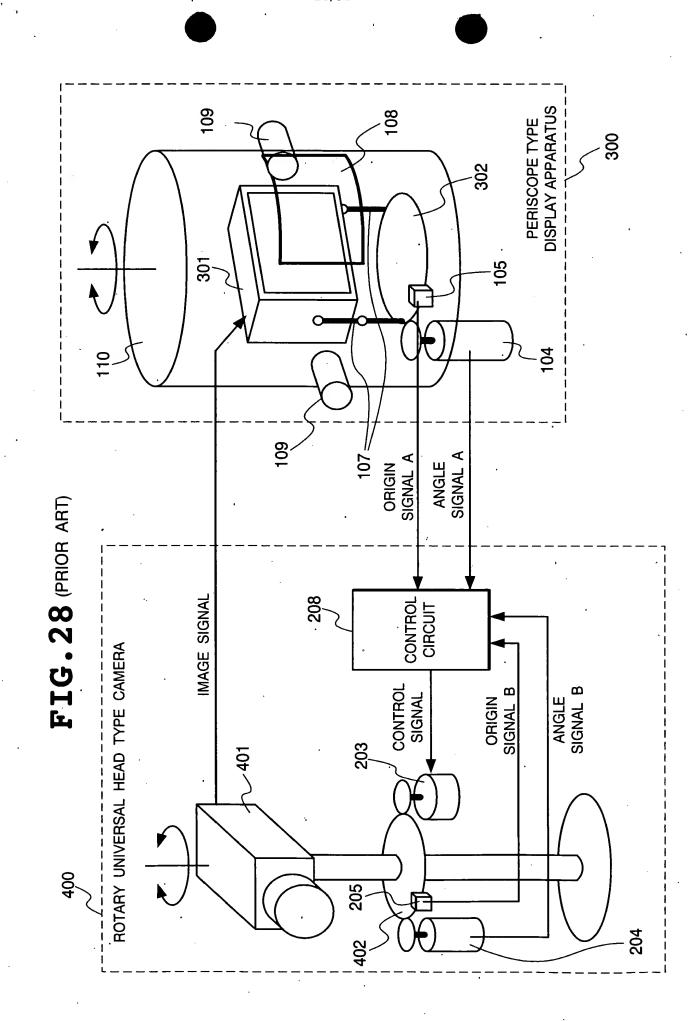




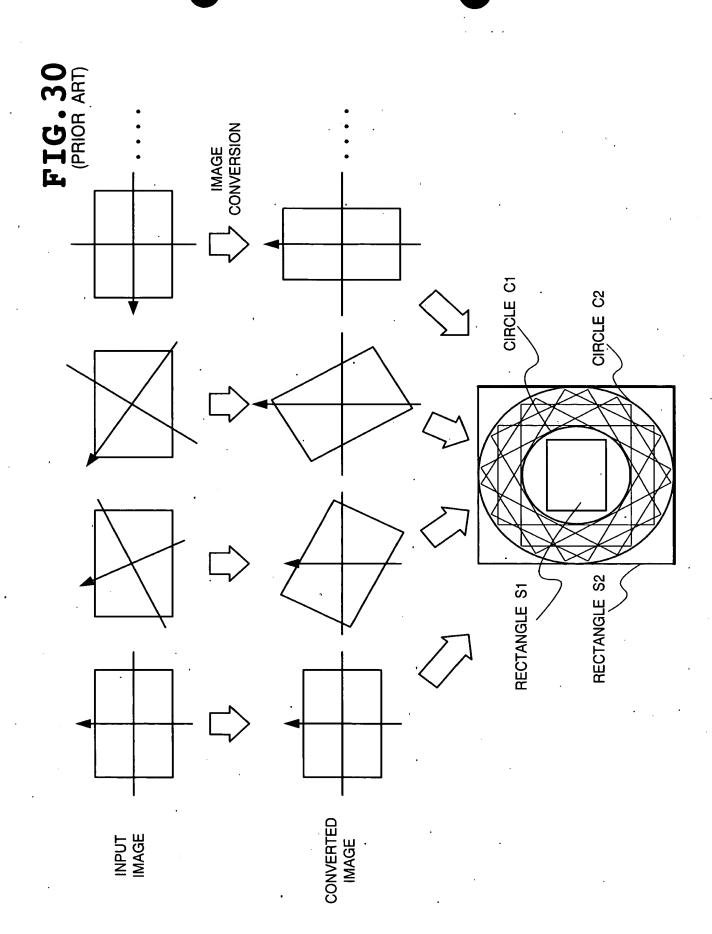




OBJECT FIG. 27 (PRIOR ART) MIRROR MIRROR CASING USER FINDER



USER 501 ROTARY MIRROR OPERATING MEANS 503 FIG. 29 (PRIOR ART) IMAGE CONVERTING MEANS IMAGE SIGNAL OPERATING SIGNAL 502 208 CONTROL IMAGE SIGNAL ANGLE SIGNAL B ORIGIN SIGNAL B CONTROL SIGNAL 202 203 ROTARY MIRROR TYPE CAMERA 205 201 204



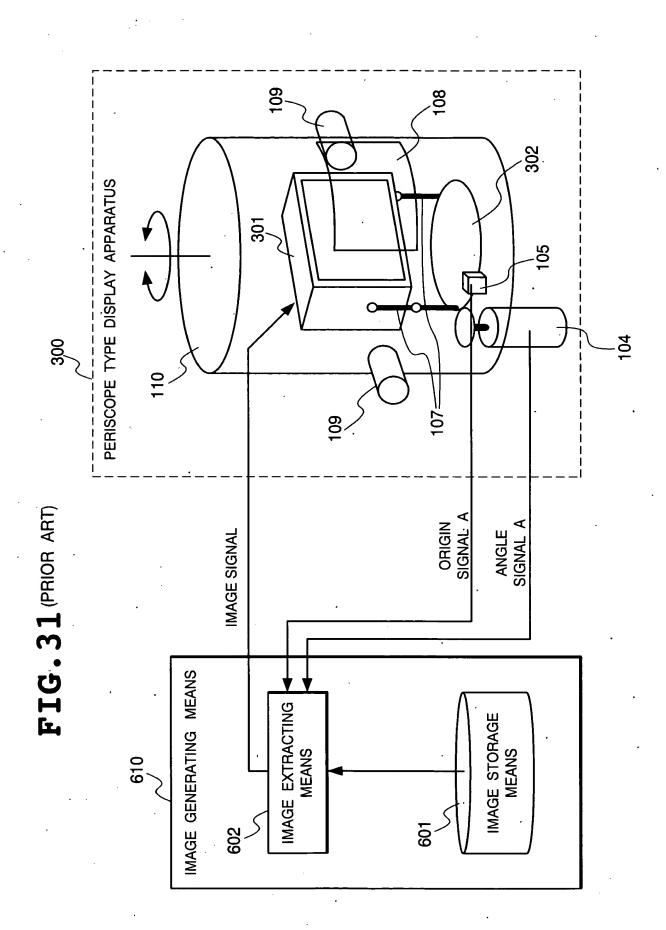
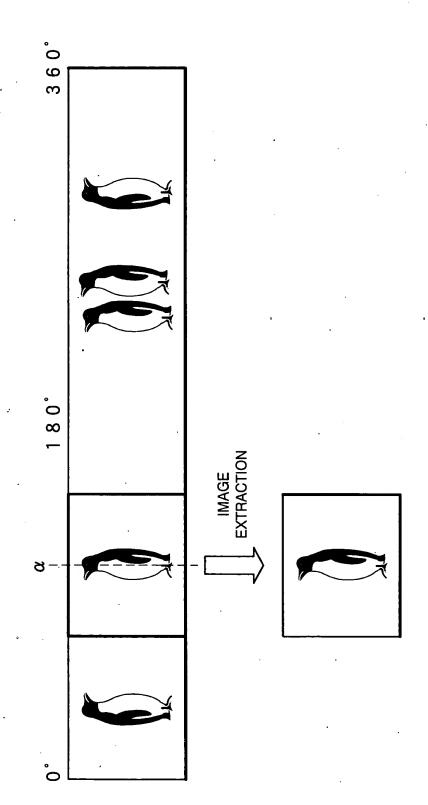
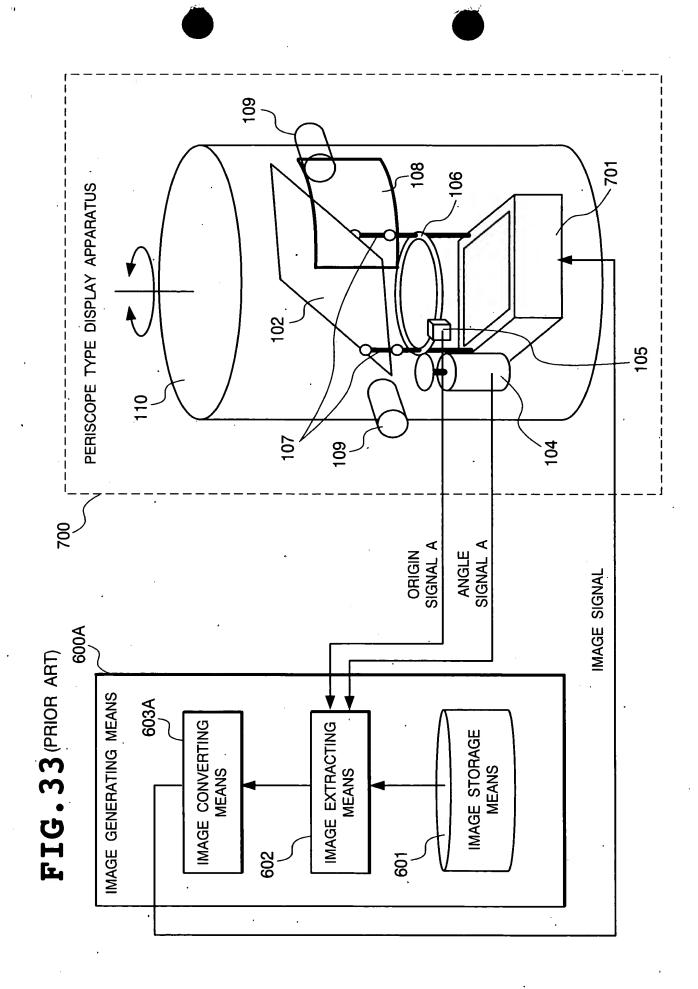


FIG. 32 (PRIOR ART)





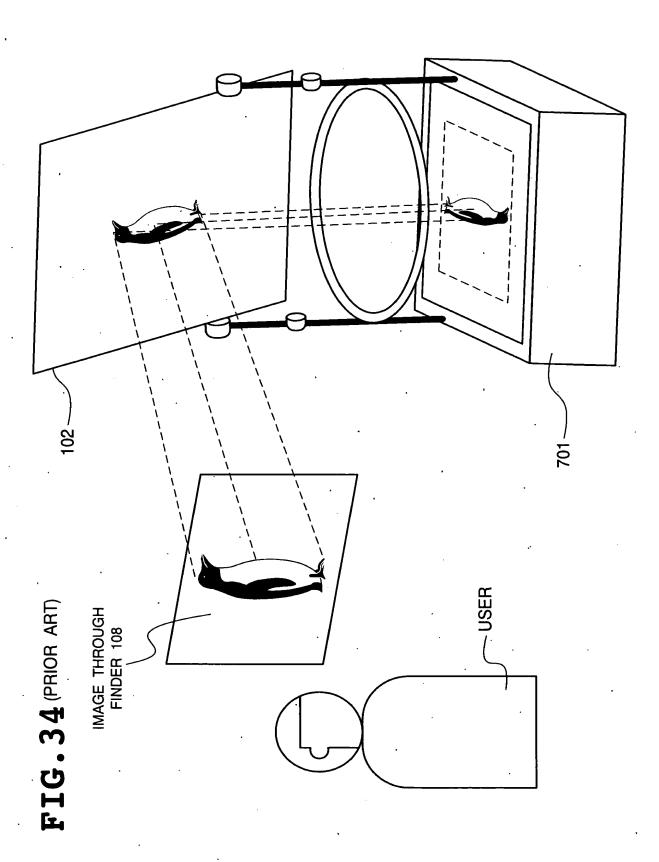


FIG. 35 (PRIOR ART)

